Computer Graphics

Dr./ Ahmed Mohamed Rabie













رابط الموقع الشخصى

http://staff.du.edu.eg/1058

Course Objectives

By the end of this course the student must be able to:

- Introduce the essentials background of the visible surface detection algorithms.
- 2. Study the reflection and illumination models.
- 3. Study rendering algorithms for 3-D objects.
- Demonstrate parametric representation of 3-D objects.
- Apply shadows algorithms, 2-D texture mapping, 3-D texture mapping, Ray tracing, volume rendering, and anti-aliasing.
- 6. Introduce fractals and 3-D computer animation.
- 7. Color space in computer graphics.

Course Contents

Introduction to Visible surface detection algorithms.

The reflection and illumination models.

Rendering algorithms for 3-D objects.

Parametric representation of 3-D objects.

3-D computer animation.

3-D computer animation.

Color space in computer graphics.

Shadows algorithms.

2-D texture mapping.

3-D texture mapping

Ray tracing

Volume rendering. Anti-aliasing; Fractals and 3-D computer animation

Course References

 Buss, Samuel R. 3D Computer Graphics: A Mathematical Introduction with OpenGL. 2003. ISBN: 9780521821032

 Shirley, Peter, Michael Ashikhmin, Steve Marschner. *Fundamentals of Computer Graphics*.
3rd ed. A K Peters/CRC Press, 2009. ISBN: 9781568814698.



Introduction

The power and utility of **computer graphics** is widely recognized, and a broad range of graphics hardware and software systems is now available for applications in virtually all fields. Graphics capabilities for both two-dimensional and three dimensional applications are now common, even on general-purpose computers.

There are a number of approaches we can take to accomplish this, and numerous **algorithms** have been devised for efficient identification and display of visible objects for different types of applications.

Some methods require more memory, some involve more processing time, and some apply only to special types of objects. Which method we select for a particular application can depend on such factors as the complexity of the scene, type of objects to be displayed, available equipment, and whether static or animated displays are to be generated.

The various algorithms are referred to as visiblesurface detection methods. Sometimes these methods are also referred to as hidden-surface elimination methods, although there can be subtle differences between identifying visible surfaces and eliminating hidden surfaces.

We can broadly classify visible-surface detection algorithms according to whether they deal with the object definitions or with their projected images. These two approaches are called object-space methods and image-space methods, respectively.

An object-space method compares objects and parts of objects to each other within the scene definition to determine which surfaces,

as a whole, we should label as visible.

In an **image-space algorithm**, visibility is decided point by point at each pixel position on the projection plane. Most visible-surface algorithms use image-space methods, although object-space methods can be used effectively to locate visible surfaces in some cases.

programming packages.

computer-graphics software: **special-**

purpose packages and general

There are two broad classifications for

Special-purpose packages are designed for **nonprogrammers** who want to generate pictures, graphs, or charts in some application area without worrying about the graphics procedures that might be needed to produce such displays.

The interface to a special-purpose package is typically a set of menus that allow users to communicate with the programs in their own terms. Examples of such applications include artists' painting programs and various architectural, business, medical, and engineering CAD systems.

By contrast, a general programming package provides a library of graphics functions that can be used in a programming language such as C, C++, Java, or Fortran.

Basic functions in a typical graphics **library** include those for specifying picture components (straight lines, polygons, spheres, and other objects), setting color values, selecting views of a scene, and applying rotations or other transformations.

Some examples of general graphics programming packages are **GL (Graphics Library), OpenGL**, VRML (Virtual-Reality Modeling Language), Java 2D, and Java 3D. A set of graphics functions is often called a computergraphics application programming interface (CG API) because the library provides a software interface between a programming language (such as C++) and the hardware. So when we write an application program in C++, the graphics routines allow us to construct and display a picture on an output device.

Graphics functions in any package are typically defined as a set of specifications independent of any programming language. A language binding is then defined for a particular high-level programming language. This binding gives the syntax for accessing the various graphics functions from that language.

Each language binding is defined to make best use of the corresponding language capabilities and to handle various syntax issues, such as data types, parameter passing, and errors. Specifications for implementing a graphics package in a particular language are set by the ISO.

The **OpenGL** bindings for the C and C++ languages are the same. Other OpenGL bindings are also available, such as those for Java and Python. A basic library of functions is provided in OpenGL for specifying graphics primitives, attributes, geometric transformations, viewing transformations, and many other operations. OpenGL is designed to be hardware independent, so many operations, such as input and output routines, are not included in the basic library.